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INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Not for submission under 37 CFR 1.99)	Application Number	10718913
	Filing Date	2003-11-21 FAX RECEIVED
	First Named Inventor	McBean, John M. OCT 16 2007
	Art Unit	3764
	Examiner Name	Brown, Michael A. OFFICE OF PETITIONS
	Attorney Docket Number	1118/A04

U.S. PATENTS								
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LIST OF PATENTS AND PUBLICATIONS FOR APPLICANTS' INFORMATION DISCLOSURE STATEMENT

INFORMATION DISCLOSURE STATEMENT BY APPLICANT	Application Number	10/718,913
	Filing Date	November 21, 2003
	Inventor	McBean et al
	Art Unit	3772
	Examiner	Brown, Michael
	Atty Docket	1118/A04

Non-Patent References		
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/MB/	BQ	Lum, et al., "A Robotic System for Upper-Limb Exercises to Promote Recovery of Motor Function Following Stroke", ICORR '99: International Conference on Rehabilitation Robotics, Stanford, CA, pages 235-239
/MB/	BR	Lum, et al., "Quantification of Force Abnormalities During Passive and Active-Assisted Upper-Limb Reaching Movements in Post-Stroke Hemiparesis", 1999, IEEE Trans on Biomed, Vol 46, No 6, pages 652-662
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	BT	Parsons, et al., "An Adaptable User Interface and Controller for a Rehabilitation Robotoc Arm, 1997, ICAR, pages 919-923
	BU	Popovic, et al., "Hybrid Assistance System-The Motor Neuroprosthesis", 1989, IEEE Transactions on Biomedical Engineering, Vol. 36, No. 7, pages 729-737
	BV	Rabischong, et al., "Control and Command of a Six Degrees of Freedom Active Electrical Orthosis for Paraplegic Patient", 1990, IEEE International Workshop on Intelligent Robots and Systems, pages 987-991
	BW	Reinkensmeyer, et al., "Guidance-Based Quantification of Arm Impairment Following Brain Injury: A Pilot Study", 1999, IEEE Transactions on Rehabilitation Engineering, Vol 7, No. 1, pages 1-11
↓	BX	Romilly, et al., "A Functional Task Analysis and Motion Stimulation for the Development of a Powered Upper-Limb Orthosis", 1994, IEEE Transactions on Rehabilitation Engineering, Vol. 2, No 3, pages 119-129

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/MB/ ↓ ↓ ↓ ↓	BY	Timoszyk, et al., "Robot-Assisted Locomotion Training after Spinal Cord Injury – Comparison of Rodent Stepping in Virtual and Physical Treadmill Environments", Department of Mechanical and Aerospace Engineering and Center for Biomedical Engineering, University of California, Irvine, 1990 IEEE International Conference, pages 1-14
	BZ	Triolo, et al., "The Theoretical Development of a Multichannel Time-Series Myoprocessor for Simultaneous Limb Function Detection and Muscle Force Estimation", 1989, IEEE Transactions on Biomedical Engineering, Vol. 36, No. 10, pages 1004-1017
	CA	Wu, et al., "A Study of Neuromuscular-like Control in Rehabilitation Robot", Proceedings of the 1996 IEEE International Conference on Robotics and Automation, Minneapolis, MN, 0-7803-2988-4/96, April 1996, pages 1178-1183
	CB	Zardoshti-Kermani, et al., "EMG Feature Evaluation for Movement Control of Upper Extremity Prostheses", 1995, IEEE Transactions on Rehabilitation Engineering, Vol. 3, No. 4, pages 324-333

Examiner Signature: /Michael Brown/

Date Considered: 01/21/2008

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↓	BB	5,112,296	05-1992	Beard et al.	602/28
↓	BC	5,835,005	11-1998	Furukawa et al.	370/400
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/MB/	BF	2002/0169402	11-2002	Hatton et al.	602/26
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	BI	Bowen, et al., "Surface EMG and Motor Control of the Upper Extremity in Muscular Dystrophy: A Pilot Study", 2002, IEEE Bioengineering Conf., pages 289-290
	BJ	Downes, et al., "Distributed Control of an Electronically Powered Hip Orthosis", 1994, IEE Control Conference, pages 24-30
	BK	Fukuda, et al., "EMG-Based Human-Robot Interface for Rehabilitation Aid", Proceedings of the 1998 IEEE International Conference on Robotics and Automation, pages 3492-3497
	BL	Harwin, et al., "Criteria for Interfacing and Control of a Powered Upper Extremity Orthosis", RERC on Rehabilitation Robotics Applied Science and Engineering Laboratories, University of Delaware/A.I. DuPont Institute, Rehabilitation R&D Progress reports, 1995, Vol. 33, pg. 215
	BM	Kawamura, et al., "A Design of Motion-Support Robots for Human Arms using Hexahedron Rubber Actuators", 1997, IROS, IEEE, pages 1520-1526
	BN	Kazerooni, "Stability and Performance of Robotic Systems Worn by Humans", University of Minnesota, Mechanical Engineering Dept., May 13-18, 1990 IEEE, Vol. 1, pages 558-563,
	BO	Kiguchi, et al., "An Exoskeleton System for Elbow Joint Motion Rehabilitation", Proceedings of the 2003 IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM 2003), pages 1228-1233
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